

Algorithm 9.5 Conditioning algorithm

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Procedure Sum-Product-Conditioning (
     $\Phi$ , // Set of factors, possibly reduced by evidence
     $\mathbf{Y}$ , // Set of query variables
     $\mathbf{U}$  // Set of variables on which to condition
)
1  for each  $\mathbf{u} \in \text{Val}(\mathbf{U})$ 
2     $\Phi_{\mathbf{u}} \leftarrow \{\phi[U = \mathbf{u}] : \phi \in \Phi\}$ 
3    Construct  $\mathcal{H}_{\Phi_{\mathbf{u}}}$ 
4     $(\alpha_{\mathbf{u}}, \phi_{\mathbf{u}}(\mathbf{Y})) \leftarrow \text{Cond-Prob-VE}(\mathcal{H}_{\Phi_{\mathbf{u}}}, \mathbf{Y}, \emptyset)$ 
5     $\phi^*(\mathbf{Y}) \leftarrow \frac{\sum_{\mathbf{u}} \phi_{\mathbf{u}}(\mathbf{Y})}{\sum_{\mathbf{u}} \alpha_{\mathbf{u}}}$ 
6  Return  $\phi^*(\mathbf{Y})$ 

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The conditioning algorithm is based on the following simple derivation. Let $\mathbf{U} \subseteq \mathbf{X}$ be any set of variables. Then we have that:

$$\tilde{P}_{\Phi}(\mathbf{Y}) = \sum_{\mathbf{u} \in \text{Val}(\mathbf{U})} \tilde{P}_{\Phi}(\mathbf{Y}, \mathbf{u}). \quad (9.11)$$

The key observation is that each term $\tilde{P}_{\Phi}(\mathbf{Y}, \mathbf{u})$ can be computed by marginalizing out the variables in $\mathbf{X} - \mathbf{U} - \mathbf{Y}$ in the unnormalized measure $\tilde{P}_{\Phi}[\mathbf{u}]$ obtained by reducing \tilde{P}_{Φ} to the context \mathbf{u} . As we have already discussed, the reduced measure is simply the measure defined by reducing each of the factors to the context \mathbf{u} . The reduction process generally produces a simpler structure, with a reduced inference cost.

We can use this formula to compute $P_{\Phi}(\mathbf{Y})$ as follows: We construct a network $\mathcal{H}_{\Phi}[\mathbf{u}]$ for each assignment \mathbf{u} ; these networks have identical structures, but different parameters. We run sum-product inference in each of them, to obtain a factor over the desired query set \mathbf{Y} . We then simply add up these factors to obtain $\tilde{P}_{\Phi}(\mathbf{Y})$. We can also derive $P_{\Phi}(\mathbf{Y})$ by renormalizing this factor to obtain a distribution. As usual, the normalizing constant is the partition function for P_{Φ} . However, applying equation (9.11) to the case of $\mathbf{Y} = \emptyset$, we conclude that

$$Z_{\Phi} = \sum_{\mathbf{u}} Z_{\Phi[\mathbf{u}]}.$$

Thus, we can derive the overall partition function from the partition functions for the different subnetworks $\mathcal{H}_{\Phi[\mathbf{u}]}$. The final algorithm is shown in algorithm 9.5. (We note that Cond-Prob-VE was called without evidence, since we assumed for simplicity that our factors Φ have already been reduced with the evidence.)